

RESEARCH ARTICLE

Rectified random cell motility as a mechanism for embryo elongation

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ABSTRACT

The body of vertebrate embryos forms by posterior elongation from a terminal growth zone called the tail bud. The tail bud is a source of highly motile cells that eventually constitute the presomitic mesoderm (PSM), a tissue that plays an important role in elongation movements. PSM cells establish an anterior-posterior cell motility gradient that parallels a gradient associated with the degradation of a specific cellular signal (FGF) known to be implicated in cell motility. Here, we combine the electroporation of fluorescent reporters in the PSM with time-lapse imaging in the chicken embryo to quantify cell diffusive movements along the motility gradient. We show that a simple microscopic model for random cell motility induced by FGF activity along with geometric confinement leads to rectified tissue elongation consistent with our observations. A continuum analog of the microscopic model leads to a macroscopic mechano-chemical model for tissue extension that couples FGF activity-induced cell motility and tissue rheology, and is consistent with the experimentally observed speed and extent of elongation. Together, our experimental observations and theoretical models explain how the continuous addition of cells at the tail bud combined with lateral confinement can be converted into oriented movement and drive body elongation.

KEY WORDS: Chick morphogenesis, Embryo elongation, Rectified motility, Tissue expansion

INTRODUCTION

Most vertebrate species exhibit an elongated body axis. This characteristic pattern is established during embryogenesis as the tissues progressively form in an anterior-to-posterior direction. Microsurgical ablation of the posterior presomitic mesoderm (PSM), which contains the precursors of skeletal muscles and the axial skeleton, severely reduces posterior elongation movements, indicating that this tissue plays a major role in the control of posterior elongation of the embryonic axis. Analysis of cell motility in the chicken embryo PSM (Bénazéraf et al., 2010) shows that there

is an anterior-posterior gradient in the activity of cells. However, locally, the motility inside the PSM of chicken and zebrafish embryos is manifested by random, undirected, Brownian-like cellular motion (Bénazéraf et al., 2010; Lawton et al., 2013). These random, diffusive movements contrast with the oriented cell intercalation movements controlling elongation of the anterior parts of the embryo. Within the PSM, this motility gradient is downstream of a chemical gradient of the secreted fibroblast growth factor FGF, as shown schematically in Fig. 1A. FGF is known to play an important role in cell motility (Delfini et al., 2005); indeed, increasing FGF concentration in the PSM causes cell motility to increase without any orientation preference (Bénazéraf et al., 2010), reducing the speed of elongation. Earlier qualitative models focused on the role of the motility gradient as a driving force for elongation (Bénazéraf et al., 2010), but how this motility gradient is related to elongation is still unclear.

The observation that at a local level cell motility is random and undirected needs to be reconciled with the emergence of global body elongation. As new cells enter the PSM, they are exposed to a high concentration of FGF and become highly motile, but do not move in an oriented manner. Owing to the confinement of motility driven by the presence of relatively immobile and stiff lateral tissues (Bénazéraf et al., 2017), the cells generate an effective mechanical pressure. Thus, a potential mechanism for the rectification that leads to the observed directional cell velocity and body elongation could be this mechanical pressure. Because the expression of FGF is highest at the posterior PSM and decreases away from it, there is a natural reduction in motility anteriorly, consistent with observations. Eventually, the effects of anterior adhesion dominate over motility and this causes cellular condensation into somites.

To quantify these processes, here we use experimental observations to measure the effective diffusivity of cells as well as their advection speed as a function of their location relative to the last formed somite. Our observations suggest a minimal microscopic cellular description of a zone of proliferating cells with high motility, which we use to develop both a quantitative cellular model and an equivalent macroscopic continuum theory, thus providing a theoretical and computational framework for body elongation. These complementary approaches yield simple expressions for the speed and scale of body elongation that are consistent with our experimental measurements, with potential implications for our understanding of outgrowth-driven morphogenesis in other settings in which FGF-driven gradients in motility and contractility drive the extension of the limb bud (Gros et al., 2010) and the gut (Nerurkar et al., 2019).

RESULTS

Experimental observations

Our experiments were carried out with chicken embryos at Hamburger-Hamilton (HH) stages 10–11 (Hamburger and Hamilton, 1992), corresponding to the period when the

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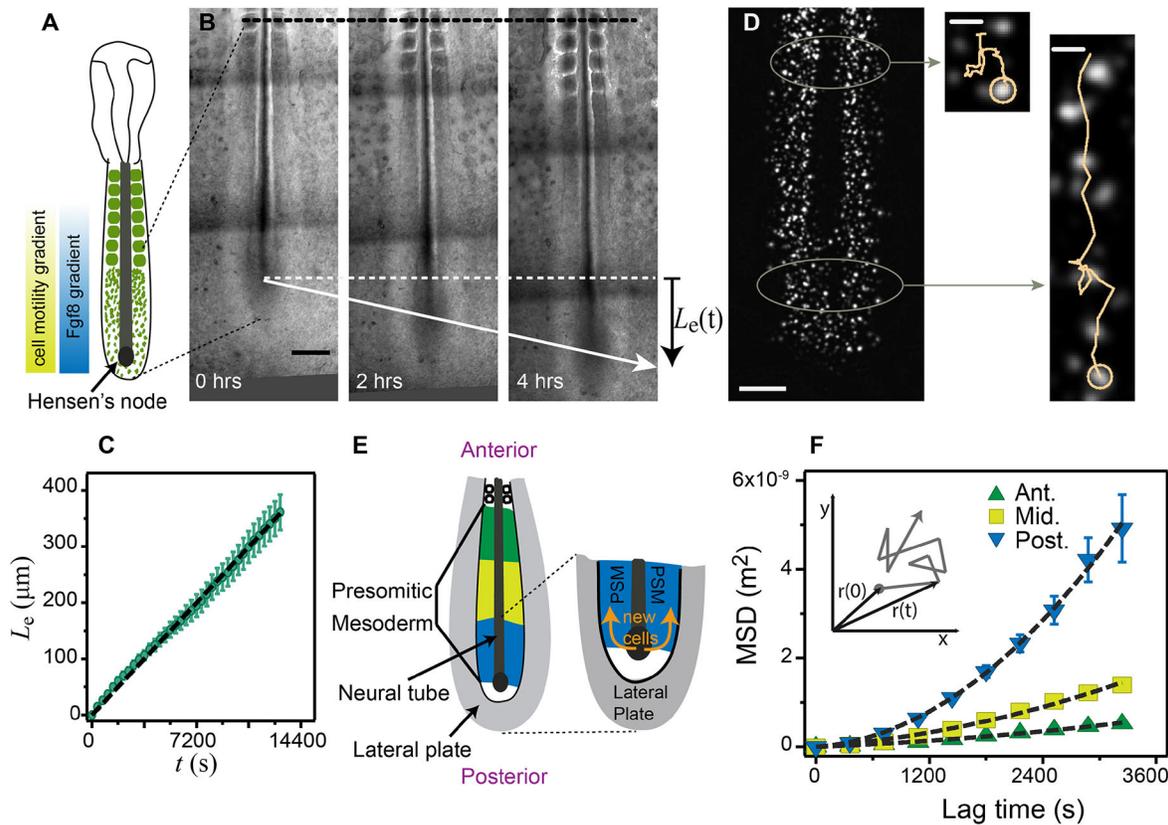


Fig. 1. Axis elongation and cell diffusion in chicken embryo. (A) Schematic of an embryo at HH stage 10. Cell motility decreases from posterior to anterior, in correlation with a decrease in FGF concentration. A gradient of cell density (green) opposite to the motility gradient is shown in the schematic embryo. (B) Time series of an elongating embryo. The black dashed line shows the reference point for tracking the posterior elongation. $L_e(t)$ is the distance over which the Hensen's node advances over time. Scale bar: 200 μm . (C) Elongation of the PSM, as a function of time. The slope gives the average elongation rate $V = (2.8 \pm 0.3) \times 10^{-2} \mu\text{m/s}$ ($n=5$, mean \pm s.e.m.). (D) Electroporated cells inside the PSM. Anterior cells advance a shorter distance than the posterior cells for the same duration of time (here 4 h). Scale bars: 200 μm (whole PSM); 25 μm (zoomed tracks). (E) Schematic of the PSM showing the three regions considered for MSD analysis shown in F, as well as the depiction of the neighboring tissues. New stem cells are generated by division of the progenitor cells inside the tail bud (TB), and move into the PSM. The movement of cells in the PSM is limited by the neural tube medially, the somites anteriorly and the lateral plate laterally. (F) Average MSD from five embryos (1000 cells) for the anterior (Ant.), middle (Mid.) and posterior (Post.) regions of the PSM. Dashed lines are fits to Eqn 1. Inset shows a sketch of random motion.

elongation of the embryo is most substantial (Denans et al., 2015). A time series of an elongating PSM is shown in Fig. 1B (see also Movie 1). To measure the elongation rate, we registered the movement of the embryo with respect to the last-formed somite at the beginning of the experiment ($t=0$) as depicted by the black dashed line in Fig. 1B, and tracked the advancement of the Hensen's node, $L_e(t)$ as a function of time. In Fig. 1C, we see that $L_e(t)$ increases linearly with time, with a mean elongation rate $V=(2.8 \pm 0.3) \times 10^{-2} \mu\text{m/s}$ (averaged from five embryos).

To evaluate the role of cell motility on overall body elongation, we then examined the movement of cells by electroporating the PSM cells with fluorescent reporters that label cell nuclei specifically (Hatakeyama and Shimamura, 2008), as shown in Fig. 1D (see also Movie 1). As a first approximation, the motion of the cells can be considered two-dimensional in the anterior-posterior and medio-lateral directions because the relative dorso-ventral depth of the PSM is small. In the reference frame of the last-formed somite at $t=0$, during a fixed acquisition time of 4 h, posterior cell trajectories showed a larger net displacement than the anterior ones, consistent with prior experiments (Bénazéraf et al., 2010). To quantify the variations of cell motility along the body axis, we divided the PSM into three regions (anterior, middle and posterior), as shown schematically in Fig. 1E, and obtained the

mean square displacement (MSD) of the cells given by $\langle \Delta r^2(t) \rangle$, where $\Delta r(t) = |r(t) - r(0)|$ defines the distance that the cell travels in a lag time t , as shown in the inset of Fig. 1F (Qian et al., 1991; Wirtz, 2009).

Decomposing the motion into a random diffusive term and an oriented drift term, we write the MSD as:

$$\langle \Delta r^2(\Delta t) \rangle = 4D\Delta t + v^2\Delta t^2, \quad (1)$$

where D is the effective cell diffusivity and v is the local population drift velocity (Qian et al., 1991). This model for cell dynamics is in accordance with previous findings for chicken (Bénazéraf et al., 2010) and zebrafish (Lawton et al., 2013) PSM elongation. Fig. 1F shows the mean MSD curves of the three regions (anterior, middle, posterior) defined in Fig. 1E and the fit to Eqn 1 (black dashed curve). From the fits, we obtain $D_{\text{Post}}=(3.5 \pm 0.7) \times 10^{-2} \mu\text{m}^2/\text{s}$, $D_{\text{Mid}}=(2.1 \pm 0.4) \times 10^{-2} \mu\text{m}^2/\text{s}$, $D_{\text{Ant}}=(1.4 \pm 0.3) \times 10^{-2} \mu\text{m}^2/\text{s}$, $v_{\text{Post}}=(2.0 \pm 0.2) \times 10^{-2} \mu\text{m/s}$, $v_{\text{Mid}}=(1.1 \pm 0.1) \times 10^{-2} \mu\text{m/s}$ and $v_{\text{Ant}}=(0.6 \pm 0.1) \times 10^{-2} \mu\text{m/s}$ (mean \pm s.e.m.). These estimates confirm the presence of a motility gradient of cells along the AP axis. [Note that one might argue that the 'drift' v could be the result of a persistent random walk rather than a drift. However, this kind of dynamics will not show a gradual change in the slope of $\langle \Delta r^2(t) \rangle$ as is observed here.]

Our observations quantify how the cells move in space and time along the PSM. When new cells are added close to the tail bud (TB), they are highly motile but move in random directions; as they move further away from the zone of proliferation in the TB, on average they gradually slow down and stop moving.

Next, we provide microscopic and macroscopic chemo-mechanical mathematical and computational models based on the observed gradient in motility and the confinement due to the more rigid lateral tissues, and show that they explain the observed rectified cell motility and the resulting posterior body elongation.

Microscopic cellular model

We start with a simple cellular model built to mimic the experimental observations in a two-dimensional setting with cells surrounded by three confining lateral walls and a free boundary corresponding to the TB. Our simplifying assumptions, which are used in both cellular and continuum models, are that the width of the PSM is constant, which is known to be approximately true for the region in which cells are motile (Bénazéraf et al., 2017), and that the cells cannot escape from the PSM owing to the constraints imposed by the somites anteriorly, the lateral plate laterally and the neural plate medially. In the discrete model, we model individual cells as soft, elastic, disks that move randomly in a manner analogous to a Brownian particle, recognizing that the cause of random movement is not related to the temperature of the environment but instead corresponds to the random activity (motility) of the cell (Berthier and Kurchan, 2013; Mallory et al., 2014). The equation of motion for an overdamped cell with coordinate $\mathbf{r}^i(t)$, assuming that inertial effects are negligible, is:

$$\gamma \dot{\mathbf{r}}^i = -\frac{\partial U}{\partial \mathbf{r}^i} + \boldsymbol{\zeta}_i(t), \quad (2)$$

where γ is the viscous friction coefficient experienced by each cell, $U(\mathbf{r}^i)$ is a potential that prevents cell-cell overlap, and $\boldsymbol{\zeta}_i(t)$ is random force. The viscous friction is a result of the interaction of cells with their environment and with each other. The repulsive interaction between cells of diameter a guarantees that two cells cannot occupy the same position; a simple form that suffices for this is given by:

$$U(\mathbf{x}) = \frac{1}{2} \sum_j \sum_{i \neq j} u_{ij}, \quad (3)$$

$$u_{ij} = k(|\mathbf{x}_i - \mathbf{x}_j| - a)^2, |\mathbf{x}_i - \mathbf{x}_j| < a \quad (4)$$

and

$$u_{ij} = 0, |\mathbf{x}_i - \mathbf{x}_j| \geq a. \quad (5)$$

Note that in our simulations the cell-cell excluded volume interactions are conservative and thus collisions are elastic but overdamped. The random force $\boldsymbol{\zeta}_i(t)$ is assumed to have zero-mean and normally distributed with Gaussian statistics such that:

$$\langle \zeta_{i,\alpha}(t) \rangle = 0 \quad (6)$$

and

$$\langle \zeta_{i,\alpha}(t) \zeta_{i,\beta}(t') \rangle = 2\mathcal{M}\gamma\delta(t-t')\delta_{\alpha\beta}, \quad (7)$$

where \mathcal{M} is the single-cell activity/motility and $\zeta_{i,\alpha}$ are the x or y components of $\boldsymbol{\zeta}_i$.

We also assume that the microscopic diffusivity of a (Brownian) cell is related to the activity by the relation $\mathcal{D} = \frac{\mathcal{M}}{\gamma}$, i.e. that the

fluctuation-dissipation theorem is valid and tantamount to assuming that the time scales on which we consider the system are long compared with the time scales for individual cell movements. We simulate the dynamics of the cells following Eqns 1-7 in a domain that has one free boundary at the PSM at which new cells are injected with the same initial activity; at each time step, we turn off the activity (and thus decrease the fraction of motile cells) with a probability which changes exponentially with time, to mimic the gradual decrease in the activity of the cells owing to a reduction in FGF concentration anteriorly, following:

$$P_r = 1 - e^{-t/\tau}, \quad (8)$$

where τ is the slowest time scale associated with kinetics of degradation of FGF, which initiates once the cell enters the TB. We will assume that the initial FGF level and τ are both constant, which is approximately true in the experimental setup for the observed times of 4 h. At the posterior-end corresponding to the TB, we assume that cells move as the body elongates owing to a constant rate at which they are added in the space that is not occupied by other cells (Fig. 2A,B). The movement of the cells from the TB to the PSM region is limited by the available space in the PSM. In our model, if there is no free space, no cells are added, so the rate of adding cells is limited by the motion of the TB, the diffusion and advection of cells away from the TB and the maximal cell packing density ρ_0 [the ratio of the area covered by the cells (disks) to the total PSM area]. We do not include cell division in our model, because it has been shown that interfering with cell division in the PSM does not affect the tailbud elongation considerably during the time scale of our analysis (Bénazéraf et al., 2010).

The TB boundary is modeled as a wall of immobile cells attached to their neighbors by elastic springs with spring constants, $k_{chain}=2k$, and allowed to move posteriorly as a result of the mechanical pressure exerted by the motile cells anterior to it. Our simulations show that after an initial transient state, the motion of the wall reaches a steady state whereby cells added at a constant rate cause the wall to move at a constant velocity (Movie 2). The quasi-one-dimensional dynamics manifest in the simulations arises because of the impermeable boundary conditions in the direction perpendicular to the direction of elongation.

The fraction of motile cells is much larger near the moving wall, and as one moves anteriorly, this density falls off quickly because of the decrease in FGF activity. Changing FGF activity by changing τ , and thus varying the probability with which each individual cell stops moving (and therefore the total fraction of moving cells), changes the velocity and motility profiles (see Fig. 2C,D).

To understand these numerical results qualitatively, we note that a new cell can be added next to the (moving) boundary ($x=a, y \in [0, Y_{max}]$) only when there is a gap of order of the size of one cell a (see Fig. 2B). Thus, our model is a cellular analog of the Brownian ratchet introduced in the context of molecular polymerization (Peskin et al., 1993). In the PSM region where the internal tissue resistance to cell motion dominates any external resistance, as in our simulations, the rate of elongation is limited by the waiting time for a gap to open that allows for the addition of a cell of size a , i.e.

$T_a \sim \frac{1}{\rho_0 \mathcal{D}}$. Here, \mathcal{D} is the activity-driven diffusivity of a single cell (consistent with Eqn 1). In this limit of diffusion-limited elongation ($T_a \ll \tau$), the speed of elongation scales as a/T_a , i.e.:

$$V \sim a\rho_0 \mathcal{D}. \quad (9)$$

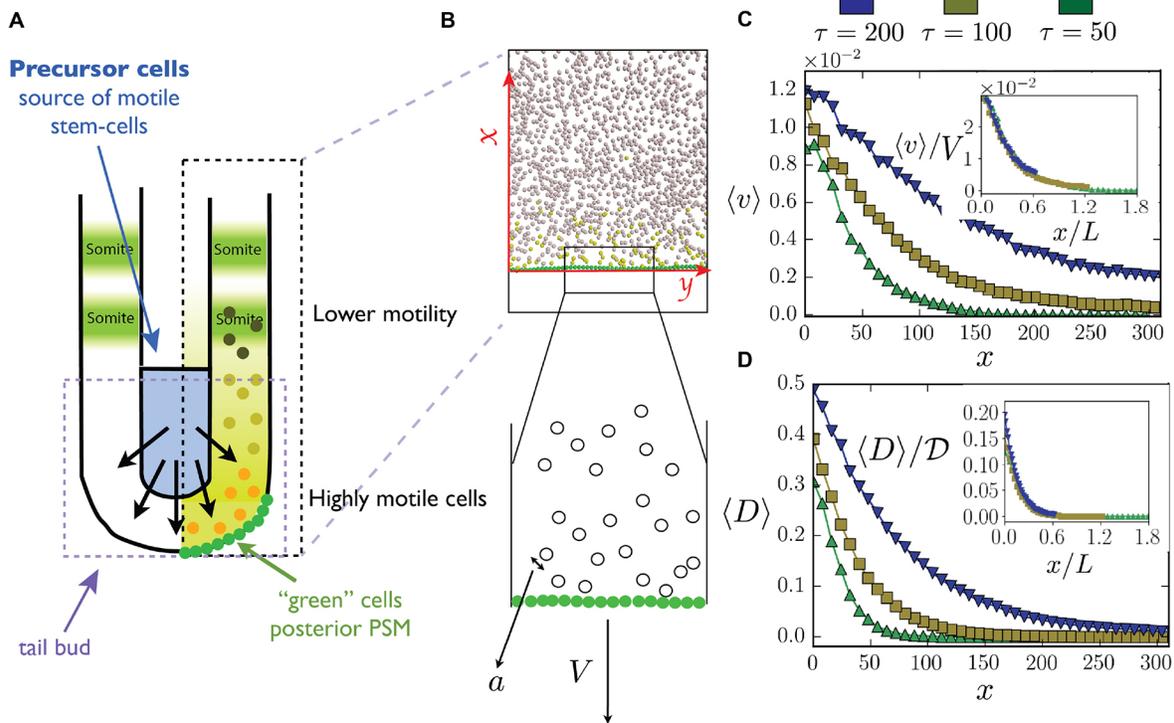


Fig. 2. Microscopic cell-based simulation. (A,B) Schematic view of the presomitic mesoderm used as a basis for cellular simulation. Yellow and gray spheres represent motile and immotile cells, respectively. The green spheres form a connected wall, which represents the border of the TB, and move in response to pressure applied by the motile cells. The wall velocity is V and the cell diameter is a . (C,D) Velocity and motility profiles for different activity decay rate τ values are calculated as in the experiments, by fitting to Eqn 1. Insets: Scaling x by L , $\langle v \rangle$ by V and $\langle D \rangle$ by \mathcal{D} , shows that the curves collapse onto each other, demonstrating that L is the relevant length scale over which cells are motile. Here, we used $\mathcal{D}=2.5$, $k=100$, $a=1$ and $\gamma=50$ in simulation units. See section 2 in the supplementary information.

Similarly, the length scale over which the fraction of motile cells falls off exponentially is:

$$L \sim a\rho_0\mathcal{D}\tau. \quad (10)$$

We note that the other limit, i.e. $\tau \ll T_a$ corresponding to adding cells that are not active, will lead to a jammed state and is not relevant here. In Fig. 2C,D, we show the decay in the speed of the cells and the effective diffusivity as a function of the distance from the TB for different values of τ . In the inset, we see that the rescaled elongation velocity and cell diffusivity using the relations shown in Eqns 9 and 10 as a function of location from the wall is consistent with our simple scaling arguments. However, as can be noticed from the ordinate in the inset of Fig. 2C, the wall velocity in our simulations, $V \sim \rho_0\mathcal{D}a \gg v$, is a consequence of the collective effect of elongation driven by the addition of multiple cells. To test that this is indeed the case, we varied both cell diffusivity \mathcal{D} and maximal cell packing ρ_0 and confirmed that the overall elongation rate $V = \rho_0\mathcal{D}a$ (see Fig. S3) is consistent with experimental results (Fig. S4).

Macroscopic continuum theory

Although the multicellular model for the dynamics of PSM elongation provides a qualitative and quantitative model by accounting for cell addition at the TB and gradual decay in motility driven by FGF degradation, an effective coarse-grained description of the process would be even more useful. There are a few reasons for this: they crystallize the processes at play in terms of the laws of conservation of mass and momentum of an active fluid, and characterize the parameter dependences in terms of dimensionless parameters and scaling laws, both of which have the feature of being

generalizable beyond the specific case of body elongation. With this in mind, we now provide an effective macroscopic one dimensional continuum theory that links the density of motile cells $\rho(x, t)$ and the velocity field $v(x, t)$ of motile cells as a function of location x in a fixed lab frame. A hydrodynamic description of the diffusion, advection and degradation of motile cells can then be written in terms of the equations for mass and momentum balance (in the viscously dominated limit) as:

$$\rho_t + (\rho v)_x = (\mathcal{D}\rho_x)_x - \frac{1}{\tau}\rho \quad (11)$$

$$\sigma_x = (-p + \eta v_x)_x = \xi v. \quad (12)$$

The first equation describes the variations in the density of actively motile cells that also gradually decay at a rate τ , whereas the second equation characterizes how the stresses associated with the active pressure generated by the random motility of the cells causes the tissue to respond and push the TB. Here, η is the viscosity of the PSM and ξ is the viscous friction associated with motion of the elongating PSM relative to the surrounding tissues (endoderm, ectoderm, neural tube and lateral plate). We note that these friction coefficients define a characteristic viscous screening length $l_\xi \sim (\eta/\xi)^{1/2}$ that we assume is of the order of a few cell sizes, i.e. $l_\xi \sim a$.

The equations need a closure relation for the pressure; a minimal relation assumes that the active pressure is proportional to the density of motile cells $p \sim \alpha\rho$, consistent with both our microscopic model, with $\alpha \sim \mathcal{M}$, and also consistent with earlier simulations of active Brownian particles (Mallory et al., 2014). Although other relations of the form $p \sim \alpha\rho^q$ are plausible, we choose to stay with a minimal model here.

To complete the formulation of the problem, we need to specify some boundary conditions for the free-boundary problem

associated with the moving TB assuming the domain of interest to be $x \in [s(t), \infty)$, with the boundary of the TB being $s(t)$. Motile cells enter the domain at a rate proportional to the difference between their local density and the maximum cell density ρ_0 , so that the cell flux is $\mathcal{R}(\rho_0 - \rho(s))$, where \mathcal{R} is the injection rate of cells from the progenitor zone into the TB. This flux must be balanced by diffusion and advection of cells from the boundary, i.e.

$$\mathcal{R}(\rho_0 - \rho(s))|_{x=s(t)} = [-\mathcal{D}\rho_x(s) + \rho(s)\dot{s}]|_{x=s(t)}, \quad (13)$$

which is reminiscent of a generalized Stefan-like condition in moving boundary problems in solidification. It is also necessary to satisfy force balance at the moving boundary so that:

$$[-\alpha\rho + \eta v_x]|_{x=s(t)} = -F, \quad (14)$$

where F is the resisting pressure exerted by the tissue ahead of the TB, and $v(s) = \dot{s}$. In the cellular simulation, this force is a result of the dynamic friction between the wall cells and the substrate and thus depends on the velocity; here, we have assumed a more general form. Far from the TB, we assume that due to degradation of FGF, the density and velocity of motile cells vanishes so that:

$$\rho(\infty) = 0, v(\infty) = 0. \quad (15)$$

Together, Eqns 11 and 12, along with the above boundary conditions (Eqns 13-15), determine the spatiotemporal evolution of the density and velocity fields in the elongating embryo as well as the speed of elongation of the embryo itself.

To understand the dependence of the solution of Eqns 11 and 12 on the problem parameters, we can rewrite the equations in a form that depends on five dimensionless variables:

$$\Pi_1 = \frac{a}{L}, \Pi_2 = \frac{\alpha\rho_0}{\xi V^2\tau}, \Pi_3 = \frac{\eta}{\alpha\rho_0\tau}, \Pi_4 = \frac{F}{\alpha\rho_0}, \Pi_5 = \frac{\mathcal{D}}{\mathcal{R}V\tau}.$$

Here Π_1 is the ratio of the cell size a and the elongation length scale $L = \frac{\mathcal{D}\tau}{a}$, Π_2 is the ratio of the maximum active stress $\alpha\rho_0$ and the external viscous friction $\xi VL \sim \xi V^2\tau$, and Π_3 is the ratio of the internal viscous stress $\eta V/L$ and the active stress $\alpha\rho_0$. We note that the parameter $\Pi_2\Pi_3 = \frac{\eta}{\xi} \frac{1}{(\mathcal{D}/a)^2\tau^2} = l_\xi^2/L^2$, where l_ξ is the viscous screening length defined earlier (after Eqn 12). Finally, there are two dimensionless parameters associated with the boundary conditions Π_4 , which is the ratio of the external stress at the PSM boundary F and the active stress $\alpha\rho_0$, and Π_5 , which is the scaled ratio of the internal cell diffusivity \mathcal{D} and the rate of addition of cells at the PSM boundary \mathcal{R} .

By rescaling all the velocities by the interface velocity V , all the lengths by elongation length scale $L=V\tau$, and the density by the maximal close packing density ρ_0 , the dimensionless form of Eqns 11-15 can be written in terms of the dimensionless variables $\tilde{t} = t/\tau$, $\tilde{x} = x/L$ and $\tilde{\rho} = \rho/\rho_0$ as:

$$\tilde{\rho}_t + (\tilde{\rho}\tilde{v})_{\tilde{x}} = \Pi_1\tilde{\rho}_{\tilde{x}\tilde{x}} - \tilde{\rho} \quad (16)$$

and

$$-\Pi_2\tilde{\rho}_{\tilde{x}} + \Pi_2\Pi_3\tilde{v}_{\tilde{x}\tilde{x}} = \tilde{v}, \quad (17)$$

along with the boundary conditions:

$$1 - \tilde{\rho}(s) = -\Pi_5\tilde{\rho}_{\tilde{x}}(s) + \frac{\Pi_5}{\Pi_1}\tilde{\rho}(s)\tilde{v}(s) \quad (18)$$

$$-\tilde{\rho}(s) + \Pi_3\tilde{v}_{\tilde{x}}(s) = -\Pi_4 \quad (19)$$

and

$$\tilde{\rho}(\tilde{x} = \infty) = 0, \tilde{v}(\tilde{x} = \infty) = 0. \quad (20)$$

For parameter values, we assume that $\mathcal{D} \approx D(x=s(t)) \approx 0.09 \mu\text{m}^2/\text{s}$, the typical degradation time scale $\tau \approx 1-2 \times 10^4 \text{ s}$, the viscosity of the PSM $\eta \sim 10^4-10^5 \text{ Pa}\cdot\text{s}$ and the friction coefficient $\xi \approx 10^{12}-10^{13} \text{ Pa}\cdot\text{s}/\text{m}^2$ measured using the micropipette aspiration technique (Guevorkian et al., 2010) (see section 1 in the supplementary information). This yields $\Pi_1 \approx 0.005-0.08$ and $\Pi_2\Pi_3 = 0.03-10$.

Using the following parameter values $\Pi_1=0.01$, $\Pi_2=2$, $\Pi_3=1$, $\Pi_4 \approx 0.005$, $\Pi_5=0.003$, we solve the initial boundary value problem (Eqns 17-21) using a finite difference method. In Fig. 3B,C, we see that our calculated profiles for the velocity $v(x)$ and diffusivity $D(x) = \mathcal{D}\rho(x)/\rho_0$ compare well with the experimentally observed profiles, and are suggestive of a simple exponential law (see also Fig. S5). In Fig. 3B, we show that the system evolves into a steady state following a short transient (insets), with an active zone near the TB that moves at constant speed. Both the cellular motility (Fig. 3B) and diffusivity (Fig. 3C) decay towards the anterior where the FGF degrades. Comparing our numerical results for the moving average of cell velocity $\langle v \rangle$ and the rescaled diffusivity $D = \mathcal{D}\rho/\rho_0$ with the experimentally determined values as a function of position relative to Hensen's node (see Materials and Methods) we see that the profiles compare well. Furthermore, on converting the results to dimensional values, we can estimate the active stress $\alpha\rho_0 \approx 5-50 \text{ Pa}$, qualitatively similar to measurements on amniote embryos (Zhou et al., 2009; Serwane et al., 2017). From the simulations, we can also estimate the typical length associated with motility decay $L \sim 1200 \mu\text{m}$ and the length scale $l_\xi \sim 1800 \mu\text{m}$ associated with friction, which are of the same order as the experimental estimates, $L=V\tau \sim 260-520 \mu\text{m}$ and $l_\xi = \sqrt{\eta/\xi} \sim 100-500 \mu\text{m}$, 3-15 times the cell size.

A sensitivity analysis of our continuum model (see section 3 in the supplementary information) shows that the parameters Π_1 , the ratio of the cell size to the elongation length scale that arises from activity, and Π_3 , the ratio of viscous stresses to the active stress, affect the velocity and motility profile significantly. The other parameters, Π_2 , Π_4 and Π_5 , have a negligible effect on our results over a range relevant for our problem (for the range of parameter values used, see Table S3; for the associated results, see Figs S6-S8). The dependence of the length scales corresponding to the typical motility and velocity profiles as a function of the dimensionless parameters Π_1 and Π_3 is shown in Fig. S10.

DISCUSSION

In vertebrate embryos, posterior structures are formed sequentially by a combination of cell proliferation and cell motility that together leads to body elongation. Although it has long been observed that the elongation process involves the posterior displacement of the TB, the physical mechanisms underlying this have not been clearly elucidated. Here, we have quantified this process experimentally and theoretically and shown that it occurs as a result of two effects: the addition of motile cells at a boundary (the TB) and confinement both laterally and anteriorly. These two effects lead to the rectification of random cell diffusivity, which generates the forces underlying elongation and the emergence of characteristic velocity and activity/diffusivity length scales. Simple cellular models and a one-dimensional continuum framework capture the essence of the behavior in terms of a pair of fundamental dimensionless parameters that characterize the ratio of the active driving stress to the internal

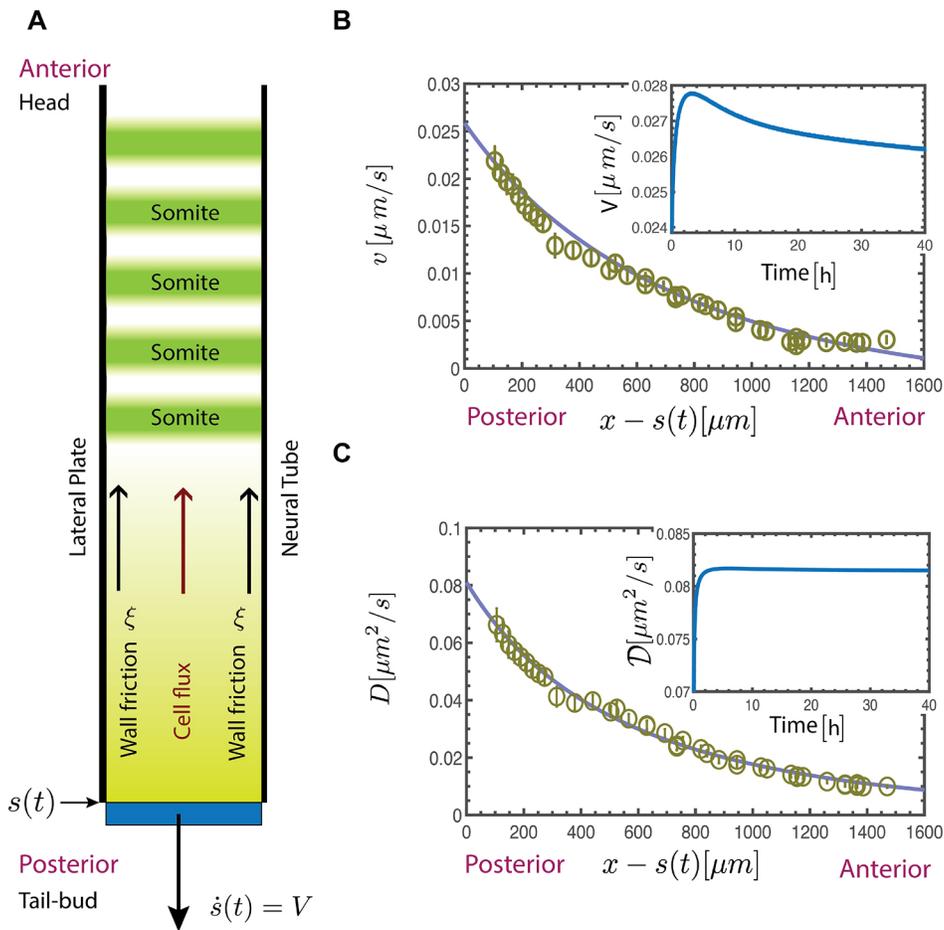


Fig. 3. Macroscopic continuum model.

(A) Schematic showing half of the PSM in the neighborhood of the TB, the position of which is $s(t)$. (B,C) Experimentally measured velocity $v(x)$ and diffusivity $D(x)$ profiles (calculated using Eqn 1) as a function of distance from the TB compares well with the results of our continuum theory obtained by solving Eqn 11 and 12 for $v(x)$ and $D(x) = D\rho(x)/\rho_0$ (continuous lines). The insets show the velocity (B) and the diffusivity (C) at the free boundary of the TB as a function of time; following a short initial transient, we see that the speed and diffusivity reach a steady state.

and external viscous stresses, and are consistent with a narrow boundary layer of activity near the TB, in agreement with observations. Natural extensions of the models include adding the effects of dimensionality, such as the lateral growth in the absence of FGF decay (Bénazéraf et al., 2010), two-dimensional compressive stresses that generate vortical flows near the TB (Xiong et al., 2020), and the gradients in viscosity from the anterior to the posterior region (Mongera et al., 2018). Such multidimensional models could also be modified to describe other embryonic outgrowths processes that exhibit graded diffusive behavior of cells downstream of FGF signaling, such as the budding of vertebrate limbs (Gros et al., 2010) and the onset of gut elongation (Nerurkar et al., 2019).

MATERIALS AND METHODS

Chicken embryo preparation and electroporation

Fertilized chicken eggs were obtained from a commercial provider (Les Couvoirs de l'Est, Willgottheim, France) and incubated at 37°C in a humidified incubator. After 24 h, HH stage 4-5 embryos were mounted on filter paper and transferred ventral side up to 35 mm agar/albumen petri dishes for injection (Chapman et al., 2001). Electroporation of the PSM was performed using H2B-mCherry or H2B-Venus nuclear markers as described previously (Bénazéraf et al., 2010). Electroporated embryos were returned to incubator and left to grow to HH stage 10-11 before imaging.

Time-lapse imaging and track analysis

The imaging procedure used here was similar to a previously described procedure (Czirók et al., 2002; Rupp et al., 2003). Briefly, the embryos were transferred to custom-made six-well observation chambers containing agar/albumin gel, and positioned ventral side up. The time-lapse imaging was

performed at 37°C using a motorized upright microscope (Leica DMR, Leica Microsystems) with a 10× objective (N.A. 0.3) and a CCD digital camera (QImaging Retiga 1300i) at a rate of 10 frames/h. At each time point, brightfield and fluorescent images of the embryo were taken at three various fields to cover the total length of the PSM. Post-acquisition processing was performed on images as described previously (Czirók et al., 2002; Rupp et al., 2003) to obtain a 2D time series. Cell tracking and trajectory analysis was performed on fluorescent images using custom-made MATLAB (MathWorks) routines. Trajectories were analyzed on 4-h long movies. To account for cell position modification due to tissue drift, we divided our movies to 1 h segments. The location of each cell was defined with respect to the node at the beginning of each 1 h trajectory. For each cell trajectory, the MSD was calculated and adjusted with Eqn 1 to obtain D and v . Further, the moving average filter, Smooth (MATLAB), was used for the plots of D and v as a function of position to obtain Fig. 3.

Discrete cell simulations

The discrete cell simulations were performed by discretizing Eqn 2 using the Euler-Maruyama method and integrating in time. In the initial state, all the particles are arranged in a square lattice (particles are slightly perturbed from the lattice) in a region that has dimensions of $80a \times 160a$. At a given time, the particles can be at $x \in [0, X_{\max}]$, $y \in [0, Y_{\max}]$, where X_{\max} is the position of the rigid boundary and $Y_{\max} = 160a$ is the lateral width. We use reduced, dimensionless units in which all energies are given in terms of a typical energy w : $U^* = U/w$, all lengths in terms of the typical cell size a , $r^* = r/a$ and masses in terms of a mass unit M , $m^* = m/M$. Using these fundamental units, we can also reduce the effective temperature, i.e. the active random motility $\mathcal{M}^* = \mathcal{M}/w$, time $t^* = t\sqrt{w/M}/a$, fraction $\rho^* = Na^3/V$ (V is the volume) and any other physical quantity of interest, where E^* , r^* , m^* , \mathcal{M}^* , t^* and ρ^* are all dimensionless.

Competing interests

The authors declare no competing or financial interests.

Author contributions

Conceptualization: O.P., L.M.; Methodology: I.R., K.G., L.M.; Software: I.R., A.G.; Validation: A.G., L.M.; Formal analysis: I.R., K.G., A.G., L.M.; Investigation: I.R., K.G., L.M.; Resources: O.P., L.M.; Data curation: K.G.; Writing - original draft: I.R., K.G., L.M.; Writing - review & editing: A.G., O.P., L.M.; Visualization: I.R., A.G.; Supervision: O.P., L.M.; Project administration: L.M.; Funding acquisition: O.P., L.M.

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S1 Viscosity measurement

We used the micropipette aspiration technique to measure the viscosity of the PSM following the same approach as in [1]. Explants of the presomitic mesoderm (PSM) were prepared with the procedure described in [2]. At a constant aspiration pressure, ΔP , the explant advances in the capillary as is shown in Fig. S1(A). The viscosity, η , is related to the flow of the explant inside the capillary via the expression $\eta = F_a/3\pi\dot{L}$, where F_a is the aspiration force given by $F_a = R_p^2\Delta P$ (here we do not consider the effect of the surface tension), where R_p is the radius of the pipette, and \dot{L} is the constant flow velocity corresponding to the slope of the aspiration curve in Fig.S1(B). This yields an estimate for the viscosity given by $\eta \sim 10^4$ Pa.s.

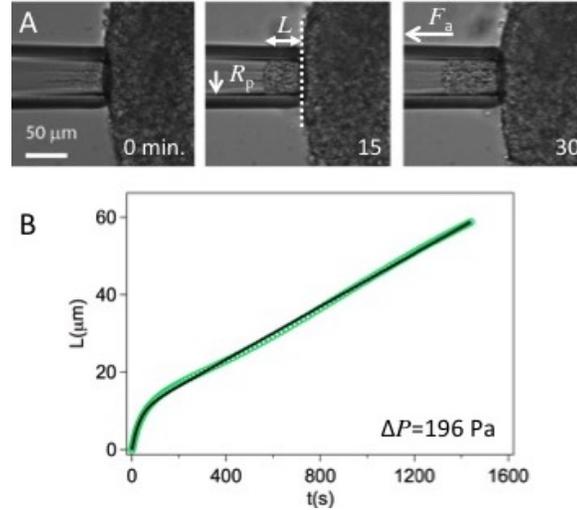


Fig. S1. Pipette aspiration to measure the viscosity of the PSM. (A) Timelapse of the aspiration of the middle section of a PSM explant (B) Aspiration curve corresponding to (A).

S1.1 PSM friction with the walls

To evaluate the friction coefficient between the PSM and the surrounding tissues (neural tube, lateral plate, ectoderm and endoderm), we use an ex-vivo approach where an explant of PSM is forced to move inside an uncoated glass capillary under the action of an external aspiration force (Fig. S2(A)). The non-specific adhesion between the explant and the glass capillary mimics the friction between the PSM and its surrounding in-vivo.

The friction coefficient of the tissue with the walls is measured by probing the advancement of the PSM explant inside the capillary at a constant aspiration pressure, ΔP . As before, the aspiration force is $F_a = \pi R_p^2 \Delta P$. The friction force is $F_f = 2\pi R_p L_{exp} k v$, where k is the friction coefficient and L_{exp} is the length of the explant. Balancing F_a with F_f gives: $\frac{R_p \Delta P}{L_{exp}} = 2k v$. We perform the experiment on explants of PSM with variable sizes and from the slope of the fitted line in Fig. S2(B), obtain $k = (1, 8 \pm 0.4) \times 10^8 \text{ N.s/m}^3$, where we note that k is depth-integrated parameter. Therefore, the bulk friction coefficient ξ scales as $\xi \approx k/w$, where $w \approx 100 \mu\text{m}$ is the width of the PSM, giving $\xi \sim 10^{12} \text{ N.s/m}^4$.

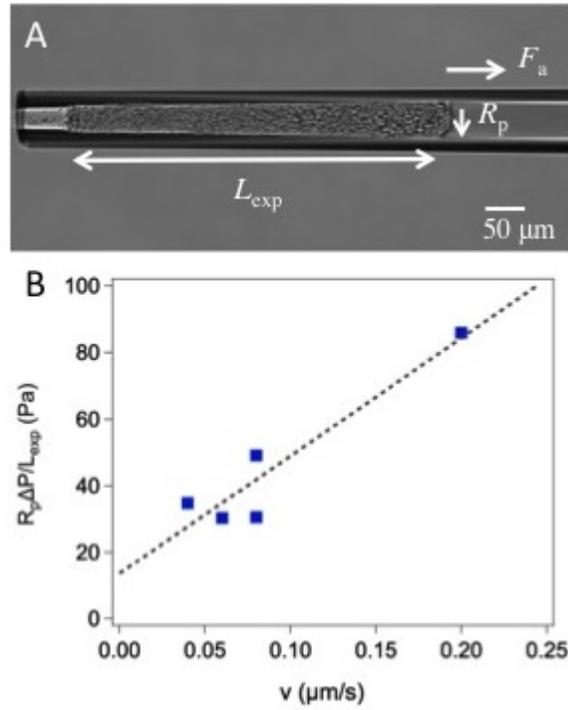


Fig. S2. Friction coefficient measurement. (A) Sliding of a PSM explant inside a capillary under a constant aspiration force. (B) The slope gives an average k from several experiments.

Table S1. The list of parameters for our microscopic-model to solve Eq. [2-8] of the main text.

| \mathcal{D} | k | a | γ | τ | ρ_0 |
|---------------|-----|-----|----------|--------------|-----------------------|
| 0.1, 0.5, 2.5 | 100 | 1 | 50 | 50, 100, 200 | 0.16, 0.24, 0.32, 0.4 |

Table S2. The list of extracted scales from the experimental data and the continuum model. We are reporting the estimate of diffusivity \mathcal{D} , decay lengthscale of motility L , decay length scale of the drift velocity L_v , length scale set by the ratio of viscous to friction dissipation l_ξ and velocity-scale V in the dimensional form.

| $L(\mu\text{m})$ | $L_v(\mu\text{m})$ | $l_\xi(\mu\text{m})$ | $V(\mu\text{m}/\text{s})$ | $\mathcal{D}(\mu\text{m}^2/\text{s})$ |
|------------------|--------------------|----------------------|---------------------------|---------------------------------------|
| 1280 | 1400 | 1800 | 0.026 | 0.08 |

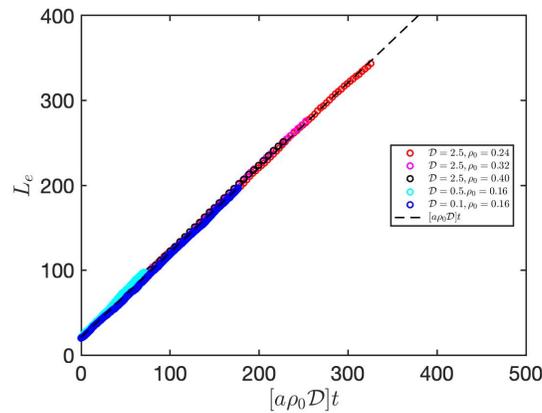


Fig. S3. Microscopic cell-based simulation: Elongation of PSM as a function of rescaled time for different value of \mathcal{D} and ρ_0 . These results are obtained by solving Eq. [2-8] of the main text.

S2 Microscopic cell-based simulations

We carried out several simulations with various values of the cell diffusivity $\mathcal{D} = 0.1, 0.5, \& 2.5$ and maximal cell packing $\rho_0 = 0.16, 0.24, 0.32, \& 0.4$. In Fig. (S3) we plot the position of TB (L_e) vs rescaled time ($a\rho_0\mathcal{D}t$), where t is simulation time and a is the cell size. All the curves from the microscopic model simulation with different \mathcal{D} and ρ_0 values collapse to the dashed line with slope 1. This indicates that the elongation rate $V = a\rho_0\mathcal{D}$, consistent with the simple scaling estimate in the main text (Eq. 9, Main Text).

In Fig. (S4) we show the drift velocity $v(x)$ and diffusivity $D(x)$ profiles from the microscopic model for $\tau = 50$ that was shown in the main text Fig.2C-D, x-axis of the microscopic model is rescaled by the appropriate

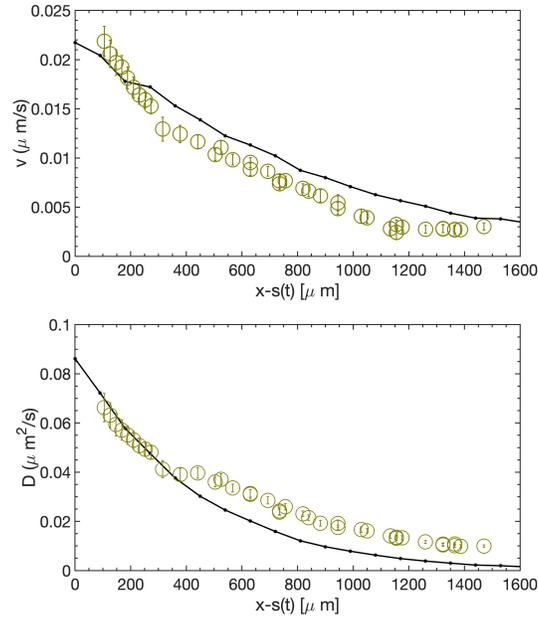


Fig. S4. Microscopic cell-based simulation: Experimentally measured velocity $v(x)$ and diffusivity $D(x)$ profiles (calculated using Eq. [1], open circles) as a function of distance from the TB compared to the rescaled numerical results of our-agent based model (black line with dots). These results are obtained by solving Eq. [2-8] of the main text.

length scale $25.6\mu m$, i.e., $x = 25.6x_{\text{Simulation}}$ (from microscopic model $L = 50$ and from the experimental data $L \sim 1280\mu m$), and y-axes are rescaled by maximal velocity ($\sim 0.026\mu m/s$) and maximal diffusivity ($\sim 0.08\mu m^2/s$), respectively, obtained from the experimental data and is compared it against the actual experimental points. $x_{\text{Simulation}}$ is in the microscopic simulation unit. Given that the simulation data comes from a minimal microscopic model with simplistic interaction potentials, the profiles agree reasonably well.

Table S1 summarizes all the parameter values used for our microscopic-model to solve Eq. [2-8] of the main text.

| <i>Run</i> | Π_1 | Π_2 | Π_3 | Π_4 | Π_5 |
|------------|---------|-----------|---------|---------|---------|
| R1 | 0.01 | 2 | 1 | 0.003 | 0.005 |
| R2 | 0.1 | 2 | 1 | 0.003 | 0.005 |
| R3 | 0.01 | 2 | 10 | 0.003 | 0.005 |
| R4 | 0.01 | 20 | 1 | 0.003 | 0.005 |
| R5 | 0.01 | 0.2 | 1 | 0.003 | 0.005 |
| R6 | 0.01 | 2 | 1 | 0.0 | 0.005 |
| R7 | 0.01 | 2 | 1 | 0.003 | 0.001 |
| R8 | 0.01 | 2 | 1 | 0.003 | 0.05 |
| R9 | 0.01 | 100 | 100 | 0.003 | 0.05 |
| R10 | 0.1 | 10^{-3} | 100 | 0.003 | 0.05 |

Table S3. The list of dimensionless parameters, scaled cell size $\Pi_1 = \frac{a}{L}$, scaled active stress $\Pi_2 = \frac{\alpha\rho_0}{\xi V^2\tau}$ (active stress/external friction), scaled internal viscosity $\Pi_3 = \frac{\eta}{\alpha\rho_0\tau}$, and the parameters corresponding to boundary condition $\Pi_4 = \frac{F}{\alpha\rho_0}$, $\Pi_5 = \frac{\mathcal{D}}{\mathcal{R}V\tau}$. These parameters are used for the sensitivity analysis of our macroscopic model.

S3 Macroscopic continuum model

In Table S2, we are reporting the estimate of diffusivity \mathcal{D} , decay lengthscale of motility L , decay length scale of the drift velocity L_v , length scale set by the ratio of viscous to friction dissipation l_ξ and velocity-scale V in the dimensional form.

Table S3 shows the range of dimensionless parameter values used in solving the eq (16)-(20), with the aim of the sensitivity of the results to these choices. R1 corresponds to the reference case used to fit the experimental data; the remaining set has one parameter which has been changed with respect to the set R1 for sensitivity analysis of our macroscopic model.

In Fig. S5, we show that an exponential profile (dashed red line) for both the velocity and the diffusivity fits well with the experimental data and the model in the posterior region close to the TB, with some expected deviation in the anterior region (run R1 of Table S3, Eq. [16-20]). The characteristic decay length for the diffusivity is $L = 1280\mu m$, while that for the velocity is $L_v = 1400\mu m$.

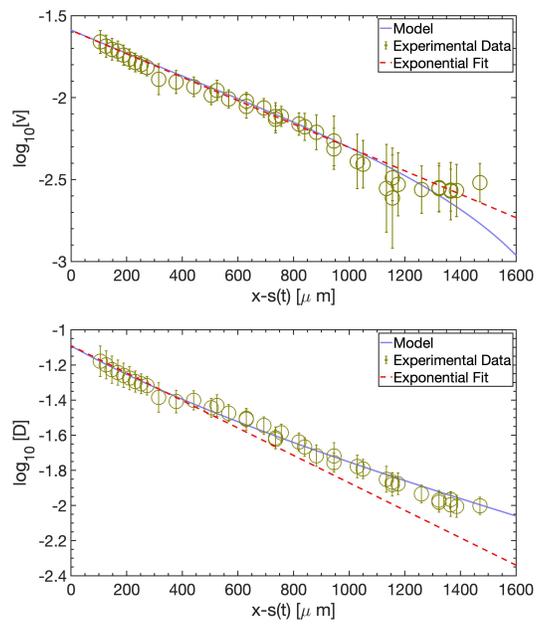


Fig. S5. Macroscopic continuum model: Log-lin fit for velocity and diffusivity profile along AP for run R1 of Table S3. These results are obtained by solving Eq. [16-20] of the main text.

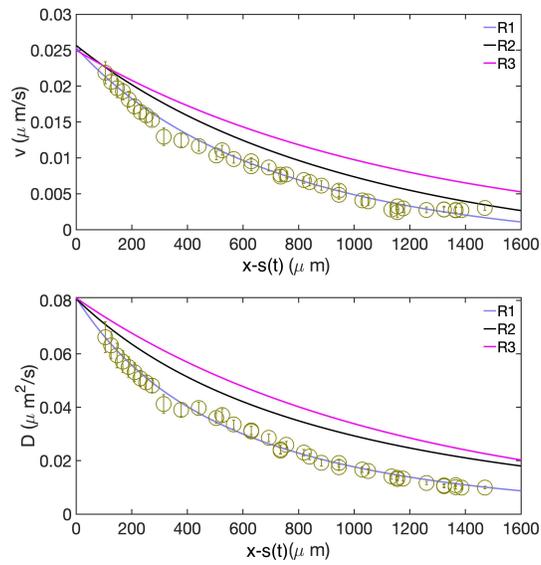


Fig. S6. Macroscopic continuum model: The velocity and diffusivity profile for varying scaled cell size (Π_1) and scaled internal viscosity (Π_3) run R2, R3 of Table S3. These results are obtained by solving Eq. [16-20] of the main text.

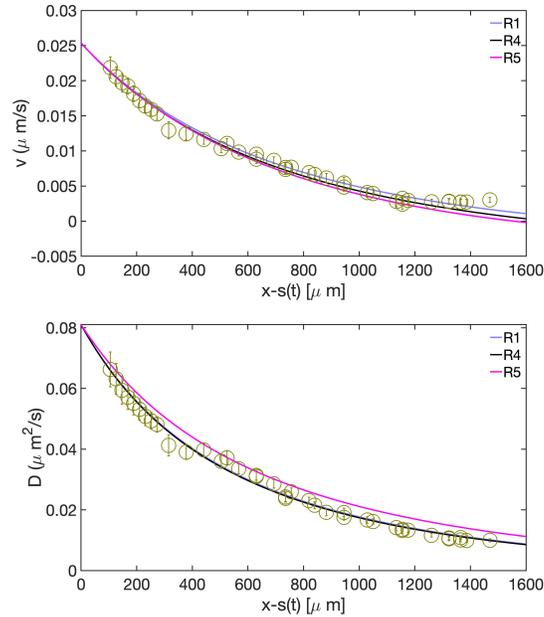


Fig. S7. Macroscopic continuum model: The velocity and diffusivity profile for varying scaled active stress (Π_2) run R4, R5 of Table S3. These results are obtained by solving Eq. [16-20] of the main text.

S3.1 Dependence of solution on the dimensionless parameters

In Fig. S6, we see that the spatial profile of diffusivity and velocity becomes flatter with an increase in the scaled cell size Π_1 (run R2 of Table S3). A similar trend is observed for the increase in the scaled internal viscosity Π_3 (internal viscosity/active stress) for run R3 of Table S3.

In Fig. S7, we plot the spatial profile of velocity and diffusivity as a function of the scaled active stress $\Pi_2 = 20$ & 0.2 (active stress/external friction) (run R4, R5 of Table S3 (Eq. [16-20])). Overall the change in the scaled external friction coefficient does not have a significant effect and the velocity and diffusivity profile is within the error-bars of the experimental data.

In Fig. S8, we show the effect of boundary conditions on the spatial profile of diffusivity and velocity associated with variations in Π_4, Π_5 run R6, R7, R8 of Table S3 (Eq. [16-20]). Overall we see that the change in

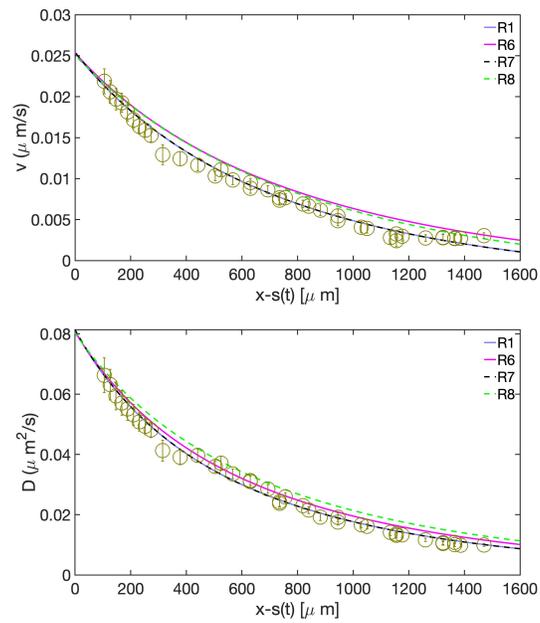


Fig. S8. Macroscopic continuum model: The velocity and diffusivity profile for varying boundary conditions (Π_4) and viscosity (Π_5) for run R6, R7, R8 of Table S3. These results are obtained by solving Eq. [16-20] of the main text.

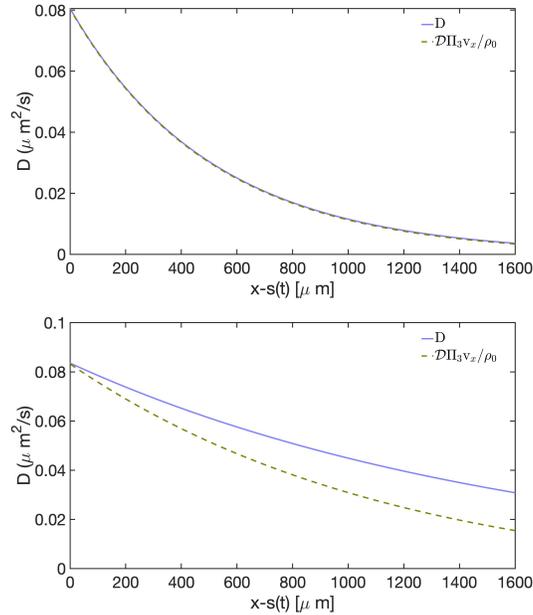


Fig. S9. Macroscopic continuum model: Plot of Diffusivity D and $\mathcal{D}\Pi_3 v_x / \rho_0$ vs distance from the TB to compare the density of motile cells $\rho(x)$ and velocity gradient $v_x(x)$ for run R9 (top panel) and R10 (bottom panel) of Table S3. These results are obtained by solving Eq. [16-20] of the main text.

boundary conditions does not affect the profile significantly and the velocity and diffusivity profile is within the error-bars of experimental data.

In Fig. S9, we plot the diffusivity $D(x) = \rho(x)\mathcal{D}/\rho_0$ and $\mathcal{D}\Pi_3 v_x / \rho_0$ profiles for two extreme values of scaled active stress $\Pi_2 = 100$ & 10^{-3} (active stress/external friction) (run R9-R10 Table S3). These plots will give us a comparison between the two contribution in LHS of Eq. [17], i.e., density of motile cells $\rho(x) = D(x)\rho_0/\mathcal{D}$ and $\Pi_3 v_x$. From Eq.(17) one can deduce that for very large values of Π_2 the friction term will be relatively small, and therefore the density $\rho(x)$ will track $\Pi_3 v_x$ as can be clearly seen (Run R9, top panel Fig. S9). For small values of Π_2 , all the terms in Eq. (17) are comparable to each other and so there is no simple relation linking the density and the velocity gradient (Run R10, bottom panel Fig. S9).

S3.2 Phase Diagram

For the range of parameters where we find a good agreement of the macroscopic model with experimental results, i.e., run R1 of Table S3, we have seen that the parameters Π_1 and Π_3 affect the velocity $v(x)$ and motility $\rho(x)$ profile significantly. In Fig. S10 we show a phase diagram of the length scale corresponding to the exponential fall in the density of motile cells L (top panel) and the length scale corresponding to the exponential fall in the drift velocity L_v (bottom panel) as a function of Π_1 and Π_3 . To extract these length scales, we used an exponential fit similar to Fig. S5. The overall trend is that with an increase in scaled cell size Π_1 and Π_3 the length scales for motility and velocity increase. The colorbar in the phase diagram is the lengthscale in μm .

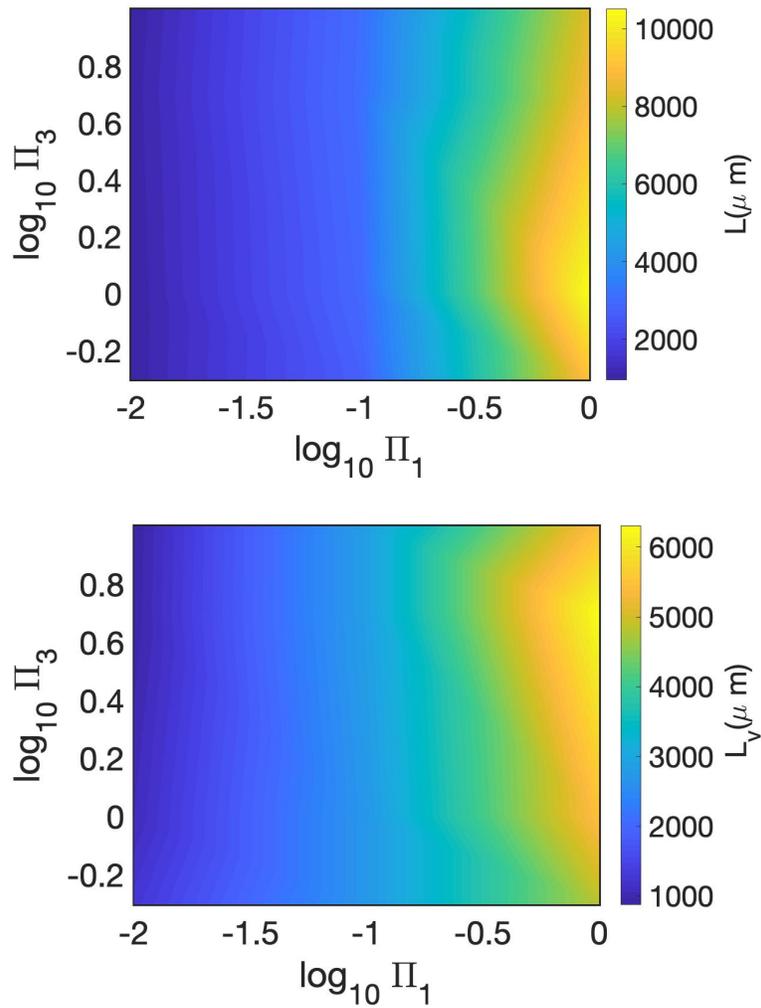
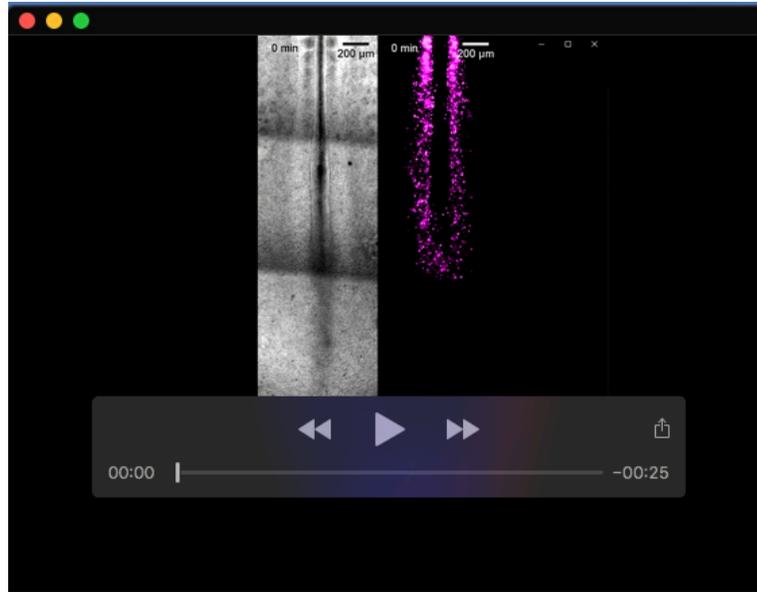


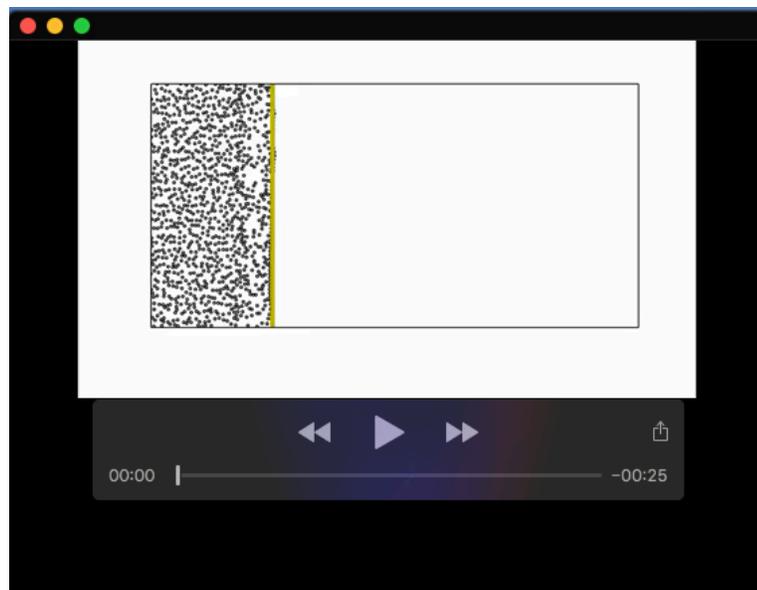
Fig. S10. Macroscopic continuum model: Phase diagrams for the decay lengthscale of motility (top panel) and decay lengthscale of drift velocity (bottom panel) as a function of Π_1 and Π_3 . The colorbar shows the lengthscale in μm . These results are obtained by solving Eq. [16-20] of the main text.

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Movie 1. Video of the movement of cells by electroporating the PSM cells with fluorescent reporters specifically labeling cell nuclei in an elongating PSM.



Movie 2. Video of the cell movement in an elongating PSM from the microscopic cellular simulation. On the left we have rigid somites where cells get reflected, on the right, we have an elastic chain, representing the Tailbud, which is moving due to active pressure applied by the motile cells. The top and the bottom side has periodic boundary conditions.